

# X-Ray computed tomography

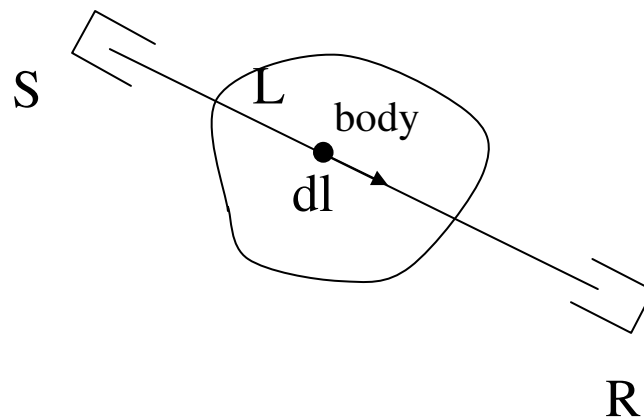
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- Radon Transform
- Fourier Slice Theorem
- Backprojection Operator
- Filtered Backprojection (FBP) Algorithm
- Implementation Issues
- Total Variation Reconstruction

# X-Ray tomography

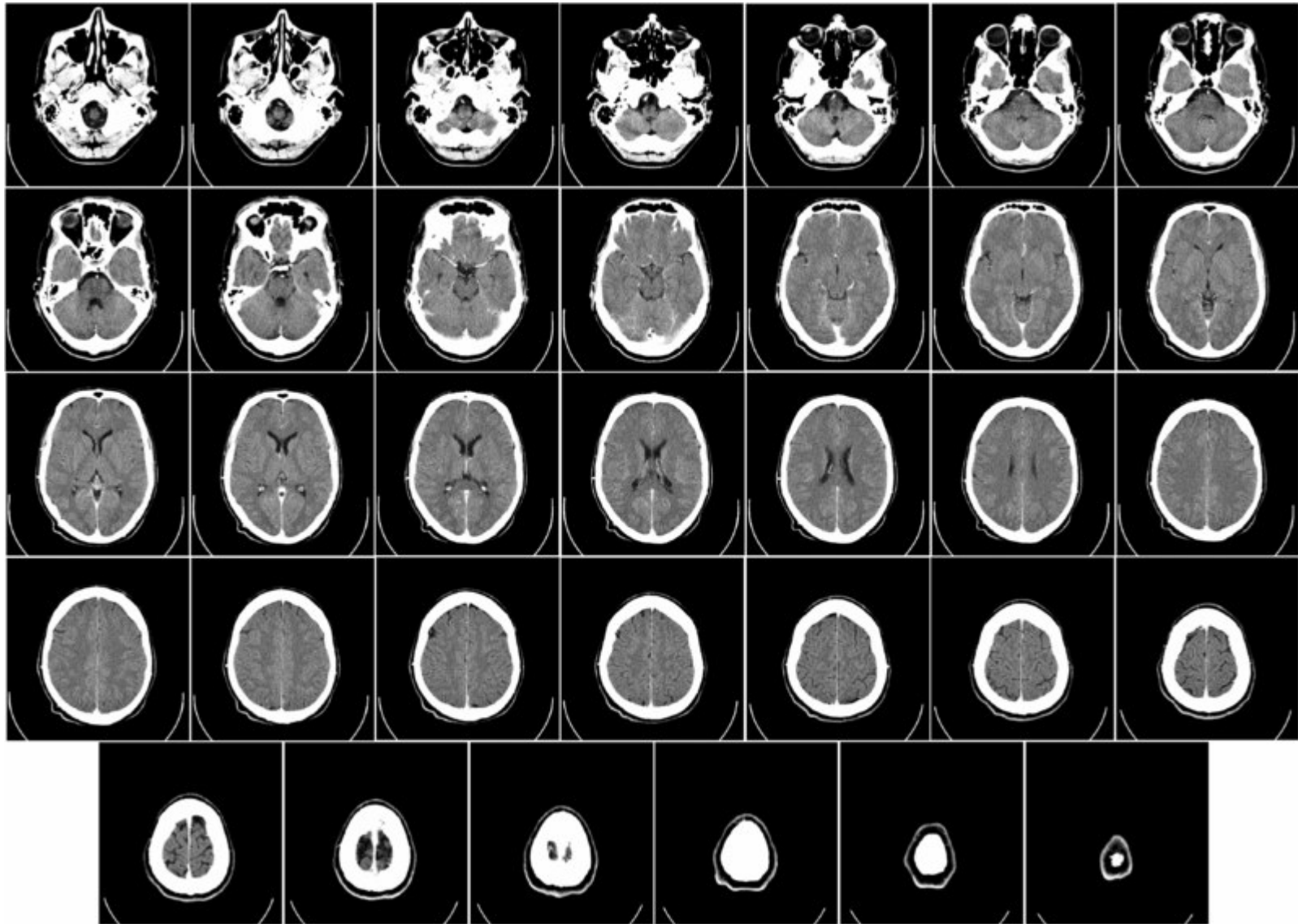
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- ❑ “Tomography” comes from Greek and means cross-sectional representations of a 3D object
- ❑ X-ray tomography, introduced by Hounsfield in 1971, is usually called *computed tomography* (CT)
- ❑ CT produces images of human anatomy with a resolution of about 1mm and an attenuation coefficient attenuation of about 1%

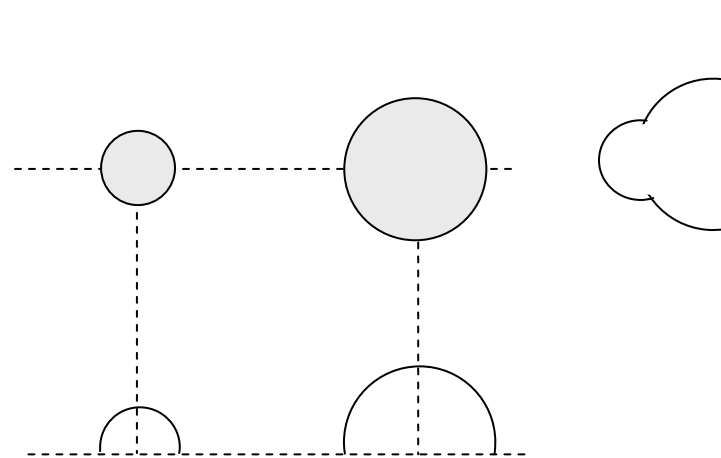
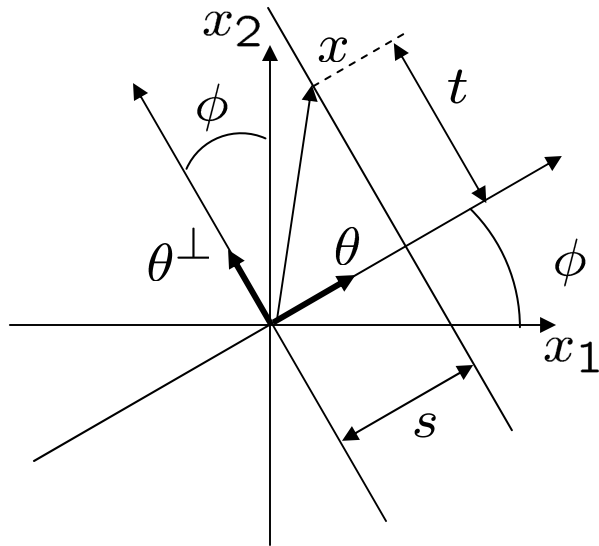


$$I = I_0 \exp \left( - \int_L f(\mathbf{x}(l)) dl \right)$$
$$\log I = \log I_0 - \int_L f(\mathbf{x}(l)) dl$$

## CT images (from wikipedia)



# X-Ray tomography



Radon transform  $(Rf)(s, \theta) = \int f(\underbrace{s\theta + t\theta^\perp}_x) dt$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} \begin{bmatrix} s \\ t \end{bmatrix}$$

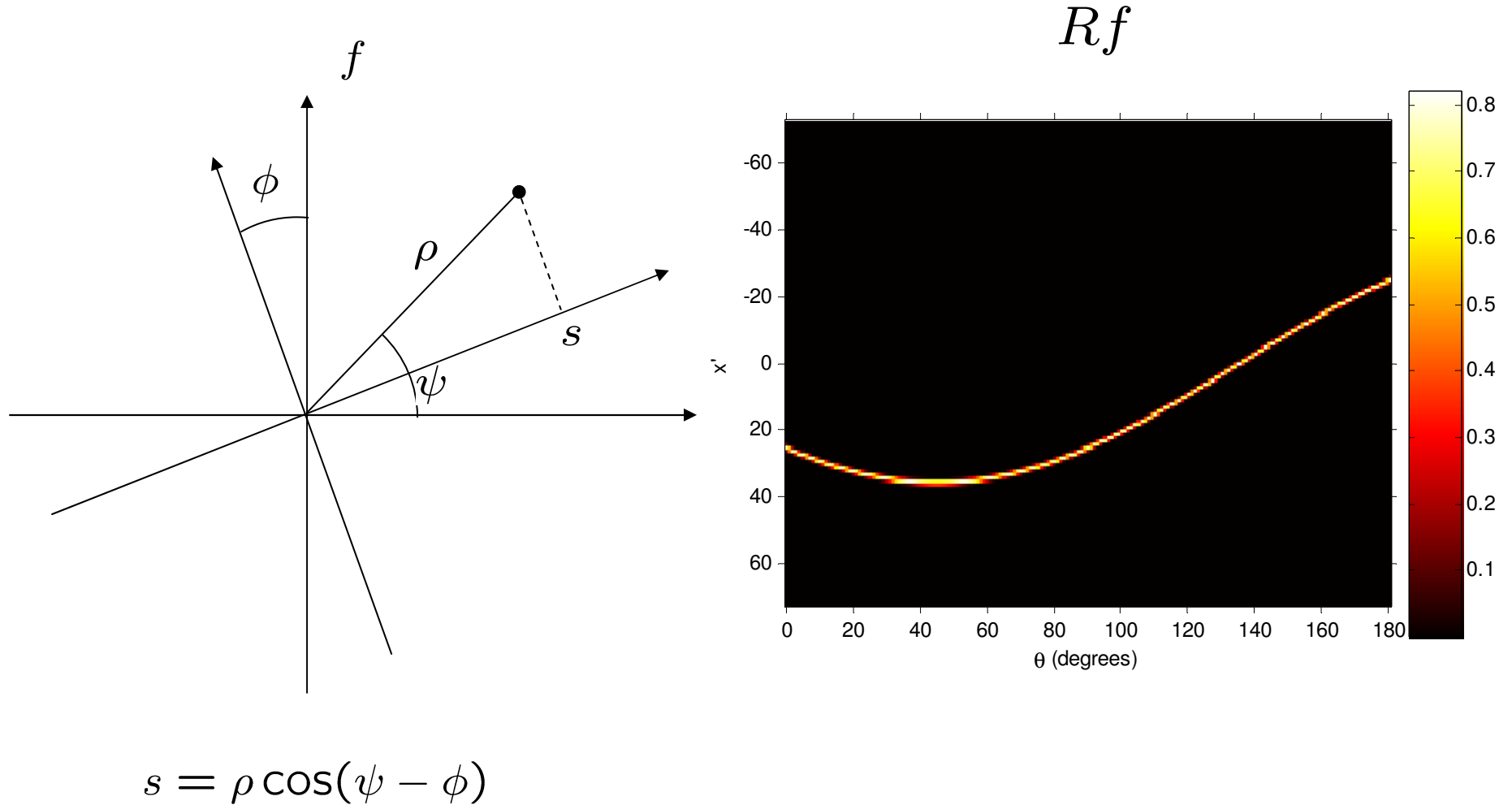
$$\theta = (\cos \phi, \sin \phi)$$

$$\theta^\perp = (-\sin \phi, \cos \phi)$$

$$-\infty < s < \infty, \quad -\pi < \phi \leq \pi$$

$$(Rf)(-s, -\theta) = (Rf)(s, \theta)$$

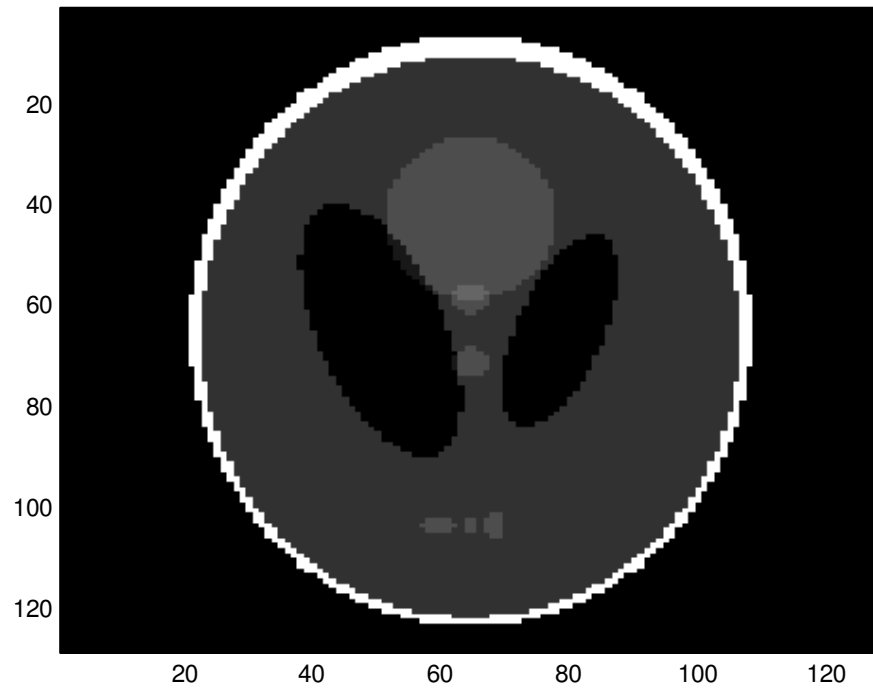
# Example of Radon transform: sinogram



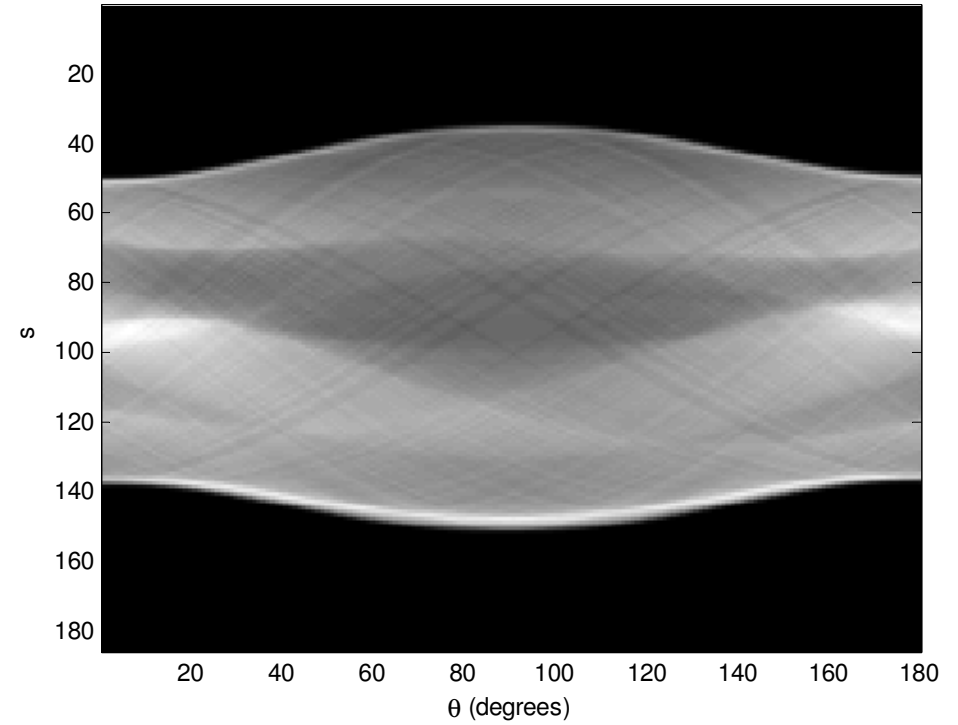
# Example of Radon transform: sinogram

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$f$



$Rf$



## Fourier slice theorem

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$$(Rf)(s, \theta) = \int f(s\theta + t\theta^\perp) dt = g(s, \theta)$$

$$\tilde{g}(\omega, \theta) = \int e^{-j\omega s} g(s, \theta) ds$$

$$= \int e^{-j\omega s} \left( \int \underbrace{f(s\theta + t\theta^\perp)}_x dt \right) ds$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix} \begin{bmatrix} s \\ t \end{bmatrix} \quad s = \theta \cdot x$$

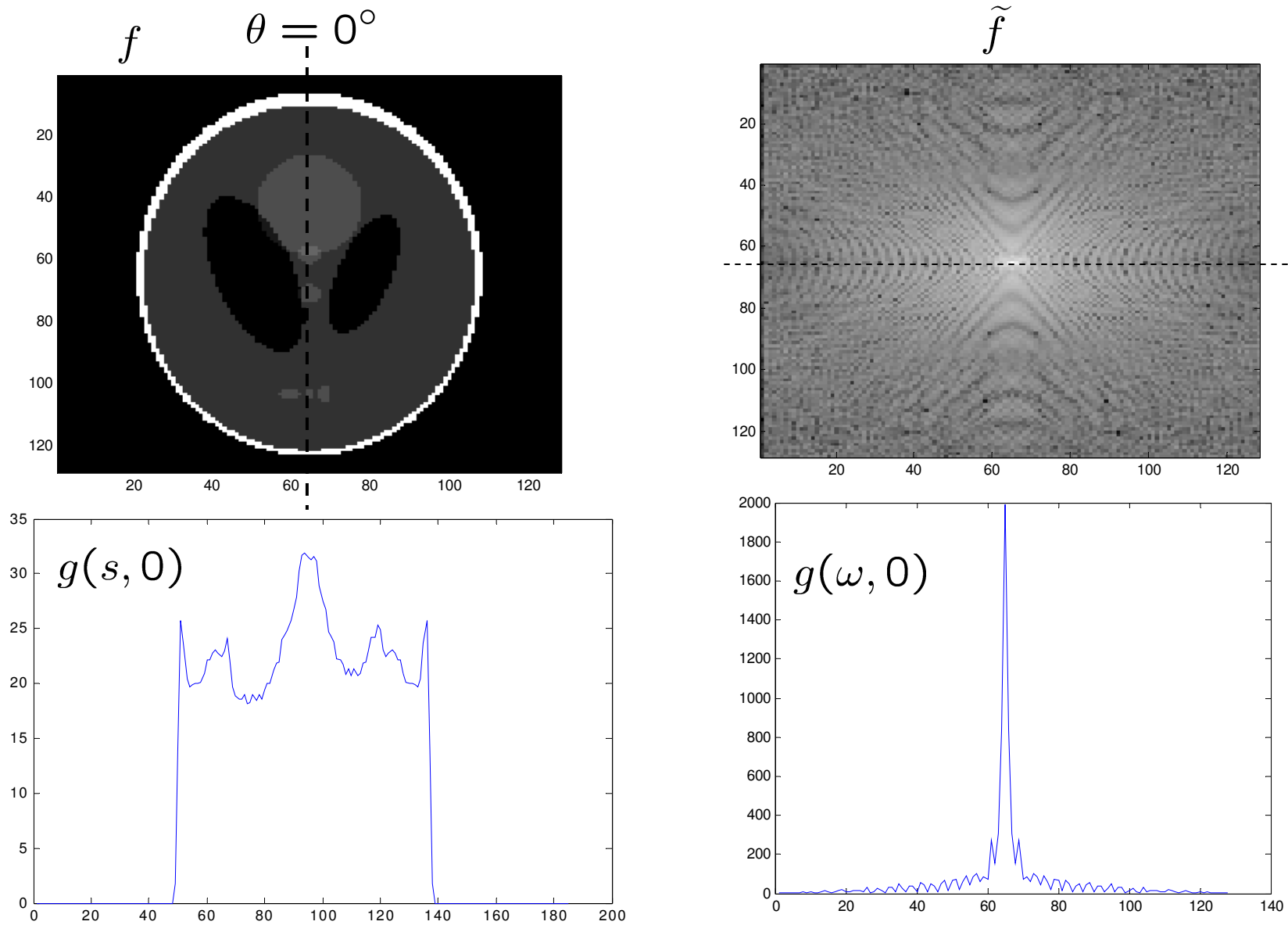
$$= \int f(x) e^{-j\omega \theta \cdot x} dx$$

$\Rightarrow$

$$\tilde{g}(\omega, \theta) = \tilde{f}(\omega\theta)$$

$$\tilde{f}(\omega_1, \omega_2) = \int f(x) e^{-j(\omega_1, \omega_2) \cdot x} dx$$

# Fourier slice theorem: illustration

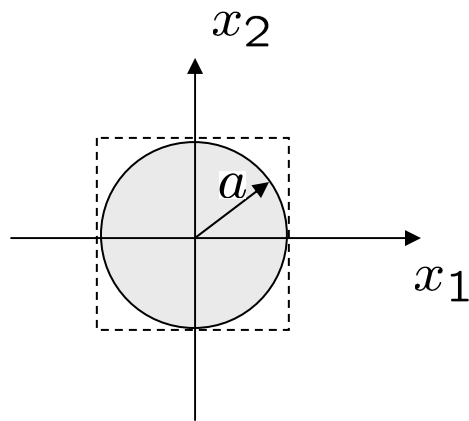




## Fourier slice theorem: consequences

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- 1- The solution of the inverse problem  $Rf = g$ , when exists, is unique
- 2- The knowledge of the the Radon transform of  $f$  implies the knowledge of the Fourier transform of  $f$



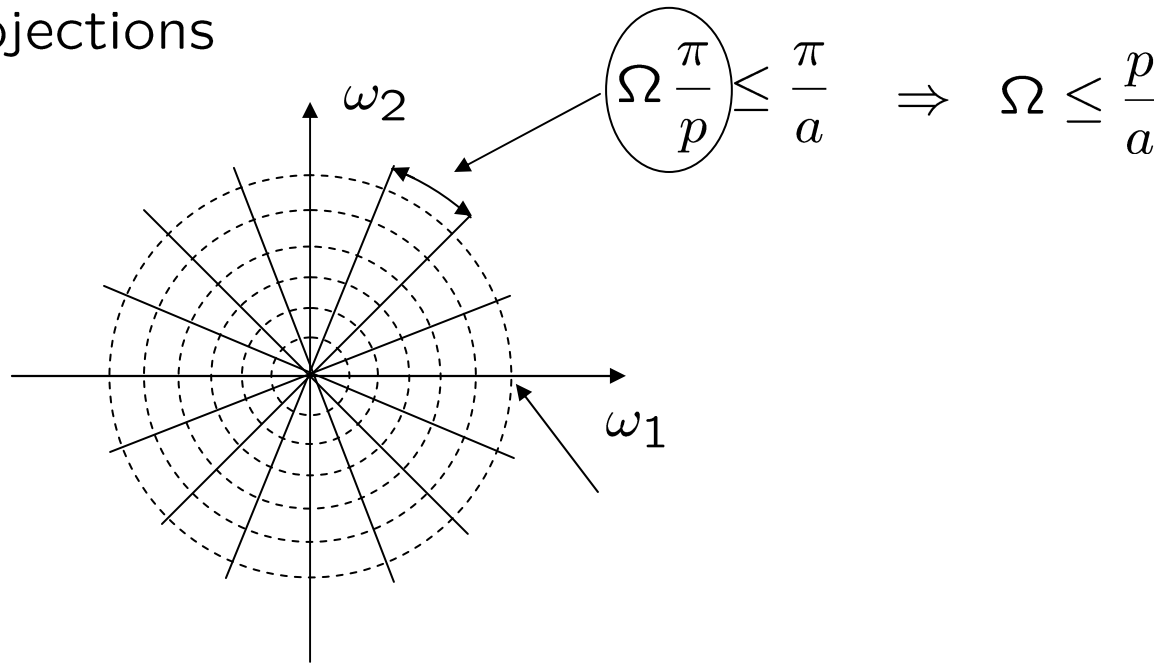
$f(x)$  is spacelimited

$\Rightarrow$

$\tilde{f}(\omega)$  can be computed from samples taken  $\pi/a$  apart

# Fourier slice theorem: consequences

$p$  projections



Assuming that  $\tilde{f}(\omega)$  is bandlimited to  $\Omega$  then it is possible to restore  $f$  with a resolution

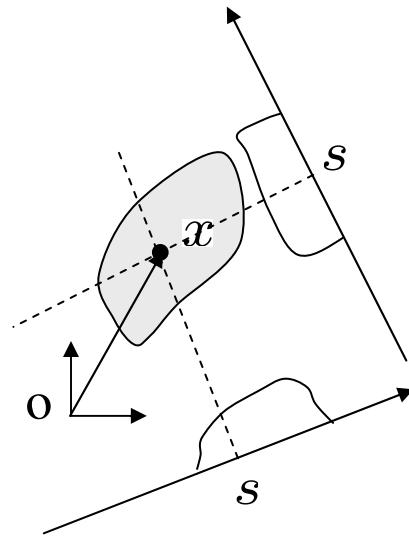
$$\delta = \frac{2\pi}{2\Omega} = \frac{\pi a}{p}$$

# Backprojection operator

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$$(R^\# g)(x) \equiv \int_0^{2\pi} g(\underbrace{x \cdot \theta}_s, \theta) d\phi$$

$(R^\# Rf)(x)$  is the sum of all line integrals that crosses the point  $x$



## Backprojection operator

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$R^\#$  is the adjoint operator of  $R$  when the usual  $L^2$  inner product is considered for both the data functions and the objects

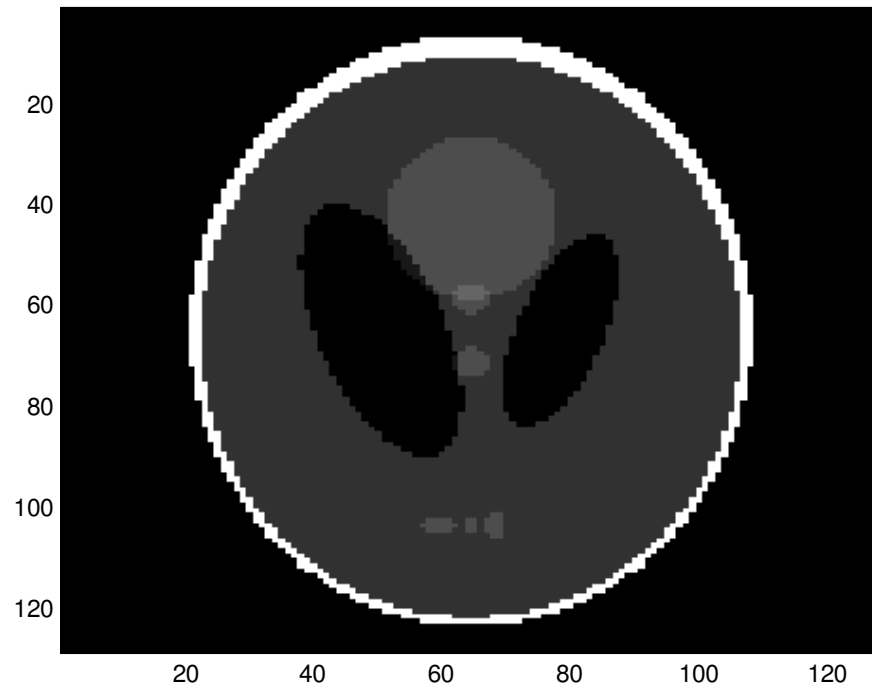
$$\begin{aligned}\langle Rf, g \rangle_{\mathcal{Y}} &= \int_0^{2\pi} \left( \int_{-\infty}^{\infty} (Rf)(s, \theta) g(s, \theta) ds \right) d\phi \\ &= \int_0^{2\pi} \left\{ \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} f(s\theta + t\theta^\perp) dt \right) g(s, \theta) ds \right\} d\phi \\ &= \int_{\mathbb{R}^2} f(x) \left( \int_0^{2\pi} g(x \cdot \theta, \theta) d\phi \right) dx \\ &= \langle f, R^\# g \rangle_{\mathcal{X}}\end{aligned}$$

# Backprojection operator

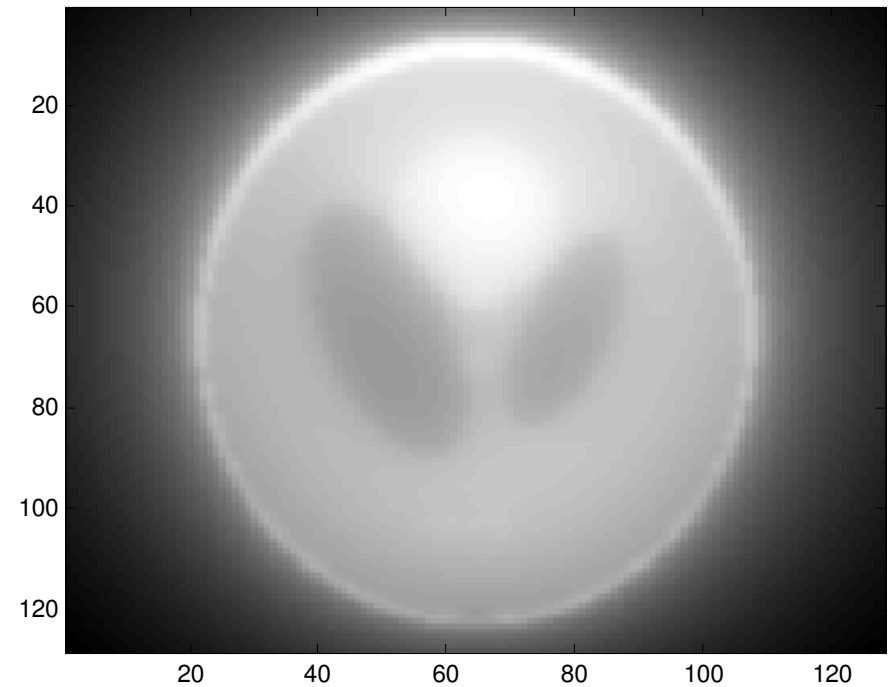
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$$(R^\# Rf)(x) = 2f(x) \star \frac{1}{|x - x'|}$$

$f$



$R^\# Rf$



## Filtered backprojection algorithm

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$$f(x) = \frac{1}{(2\pi)^2} \int \tilde{f}(\omega) e^{j\omega \cdot x} d\omega \quad \omega = |\omega| \underbrace{(\cos \phi, \sin \phi)}_{\theta}$$

$$f(x) = \frac{1}{(2\pi)^2} \int_0^{2\pi} \left( \underbrace{\int_0^\infty |\omega| \tilde{f}(|\omega|\theta) e^{j|\omega|\theta \cdot x} d|\omega|}_{\text{periodic function of } \phi} \right) d\phi$$

periodic function of  $\phi$

$$f(x) = \frac{1}{(2\pi)^2} \int_0^{2\pi} \left( \int_0^\infty |\omega| \tilde{f}(-|\omega|\theta) e^{-j|\omega|\theta \cdot x} d|\omega| \right) d\phi \quad \omega' = -|\omega|$$

$$= \frac{1}{(2\pi)^2} \int_0^{2\pi} \left( \int_{-\infty}^0 |\omega'| \tilde{f}(\omega'\theta) e^{j\omega'\theta \cdot x} d\omega' \right) d\phi$$

$$= \frac{1}{2(2\pi)^2} \int_0^{2\pi} \left( \int_{-\infty}^\infty |\omega'| \tilde{f}(\omega'\theta) e^{j\omega'\theta \cdot x} d\omega' \right) d\phi$$

## Filtered backprojection algorithm

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$$f(x) = \frac{1}{2(2\pi)^2} \int_0^{2\pi} \left( \int_{-\infty}^{\infty} |\omega'| \tilde{f}(\omega'\theta) e^{j\omega'\theta \cdot x} d\omega' \right) d\phi$$

From the Fourier slice theorem  $\tilde{f}(\omega\theta) = \tilde{g}(\omega, \theta)$

Defining the filtered backprojections as

$$G(s, \theta) = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\omega| \tilde{g}(\omega, \theta) e^{j\omega s} d\omega$$

Then

$$f(x) = \frac{1}{4\pi} R^\# G$$

## Summary of the filtered backprojection algorithm

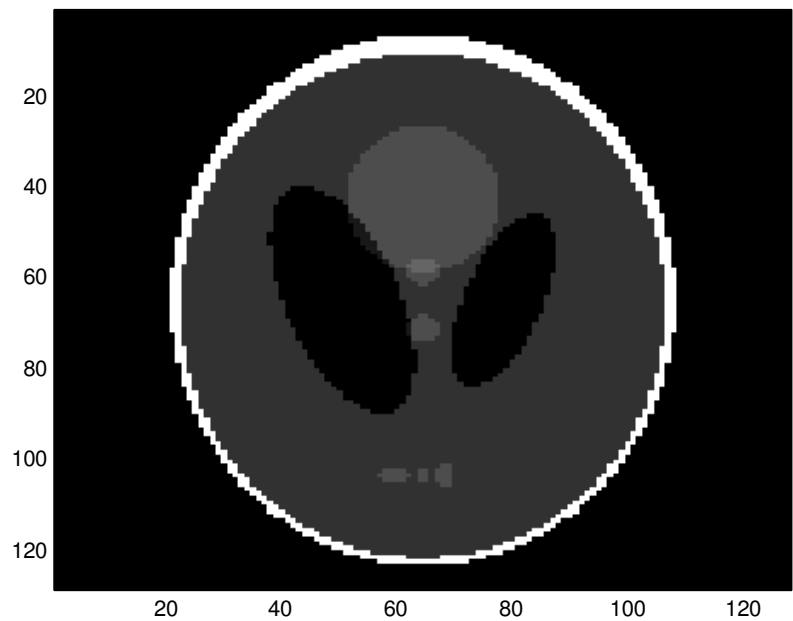
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- for each value of  $\theta$  compute the Fourier transform  $\hat{g}(\omega, \theta)$  of  $g(s, \theta)$
- multiply  $\hat{g}(\omega, \theta)$  by the ramp filter  $|\omega|$
- compute the inverse Fourier transform of  $|\omega|\hat{g}(\omega, \theta)$  to obtain the filtered projections  $G(s, \theta)$
- apply the backprojection operator to  $G(s, \theta)$ .

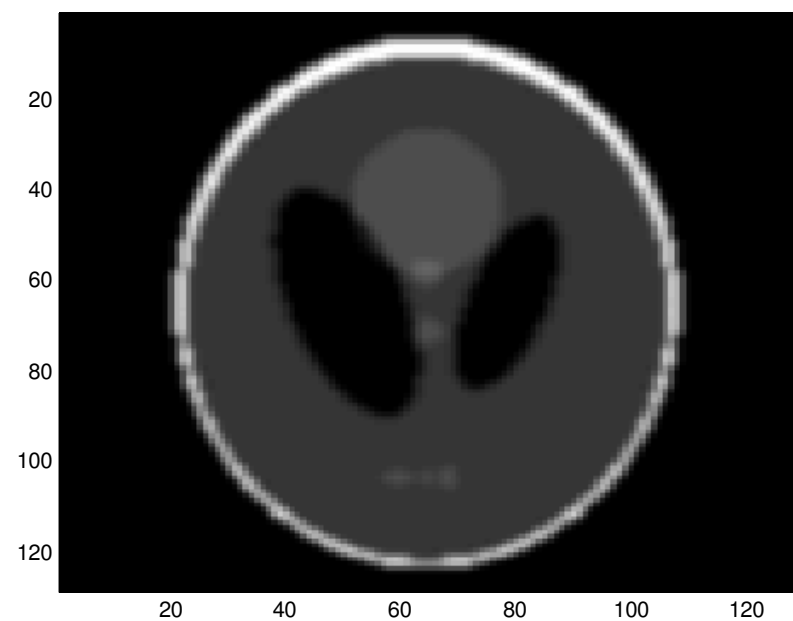


# Filtered backprojection

Hann filter



TV - Reconstruction



Ram-Lak filter

